

StretchFABRIC Sensing Element

#0SEF – StretchFABRIC Sensing Element



Technical Data Sheet

Product overview

StretchFABRIC sensors are soft, flexible, and precise making them ideal for the measurement of soft object deformation. They connect to 10-channel SPI Sensing Boards which pair with the Android and iOS data visualization apps.

StretchFABRIC sensors come bonded onto white Lycra® fabric providing an integration zone for easy sewing into garments.



Figure 1: StretchFABRIC sensor

Features

- Soft, flexible, and lightweight for unobtrusive and comfortable measurement of motion
- Easy sewing integration into garments
- Highly precise measurement of deformation

Applications

- Smart garments
- Sports and fitness
- Wearables
- VR/AR

The data displayed in this document uses aggregated test data tested at room temperature. These values are indicative only; individual sensing element performance may vary.

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1. Physical Specifications

1.1 Technical Drawing

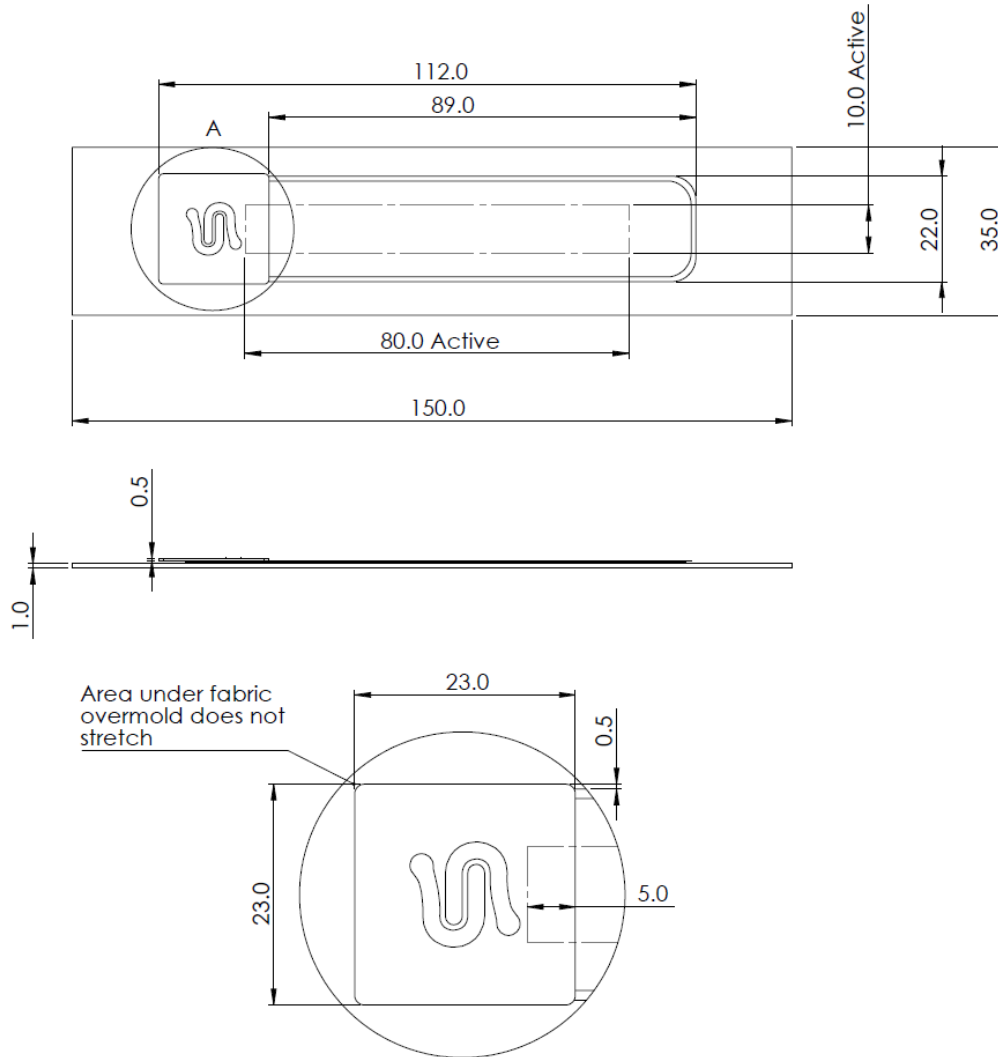


Figure 2: Engineering Drawing of a StretchFABRIC Sensing Element

1.2 Dimensions

Zone	Length (mm)	Tolerance (%)	Width (mm)	Tolerance (%)
Active Sensing Zone	80.0	±2.00	10.0	±2.00
Overall Silicone Zone	112	±2.00	22.0	±2.00
Fabric Backing	150	±4.00	35.0	±4.00
Coaxial Cable Length	1000	±1.00	0.445	-

2. Specifications

2.1 Sensing Characteristics

The data below was collected under the following testing conditions:

- The sensors underwent uniaxial stretch up to 80% stretch
- The sensors were clamped on both ends
- The sensors were pre-stretched to remove any slack

Parameter	Min	Typ	Max	Units	Notes
Base Capacitance	416	521	665	pF	
Sensitivity	6.87	8.53	10.7	pF/mm	
Noise With Standard 10 Channel Circuit (3 Sigma)	0.10	0.11	0.46	pF	
Operating Temperature Range	10.0		30.0	°C	Recommended range only
Connection Pitch		2.54		mm	

All values shown at 3 s.f.

Base capacitance includes a cable capacitance of $112 \pm 3\text{pF}$

2.2 Capacitance vs Extension

Linear Fit

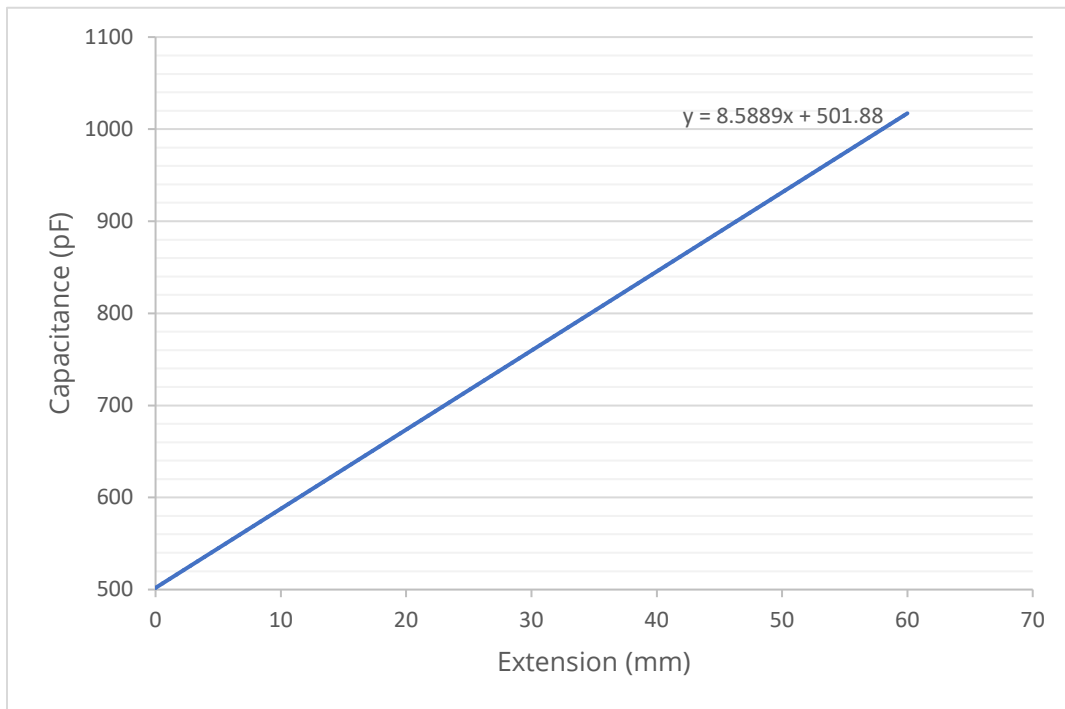


Figure 3: Typical StretchFABRIC Sensing Element performance based on a linear fit

Quadratic Fit

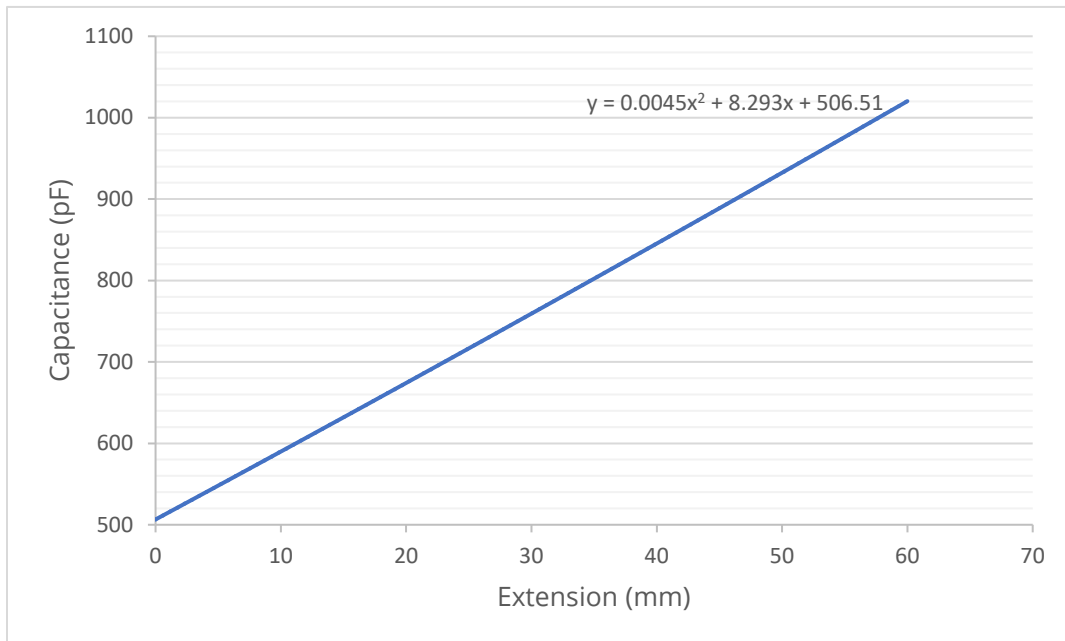


Figure 4: Typical StretchFABRIC Sensing Element performance based on a quadratic fit

2.2 Preliminary Temperature Testing Data

Summary

A single standard StretchFABRIC sensor was cycled between 80 °C and 22 °C five times, with the sensor's output recorded against temperature in real-time.

Equipment Used

- 1x StretchFABRIC sensor
- 1x 10-channel circuit
- 1x TENMA 72-7712 Digital thermometer
- 1x Thermo scientific oven – Lackrockenschrank LUT 6050 F

Test Method

Two temperature probes were embedded to the top of the sensor's surface with wet silicone and then cured.

Real-time temperature and capacitance values were recorded as the sensor was heated to over 82 °C and then cooled back down to 22 °C.

Results

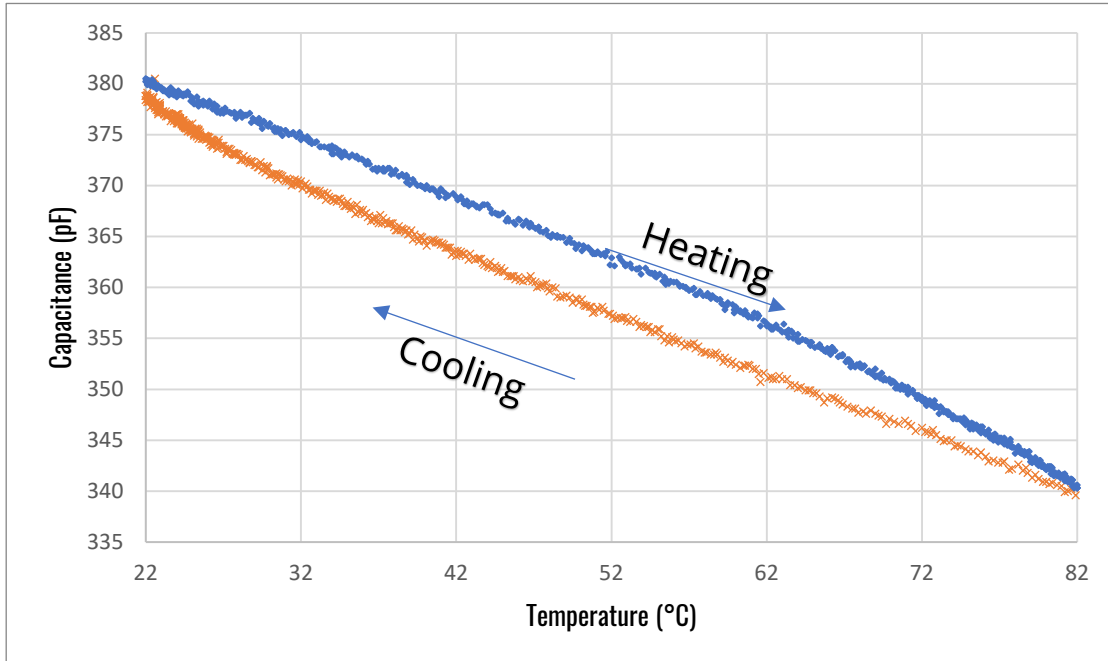


Figure 5: Temperature response of a StretchFABRIC sensor over one cycle of heating and cooling

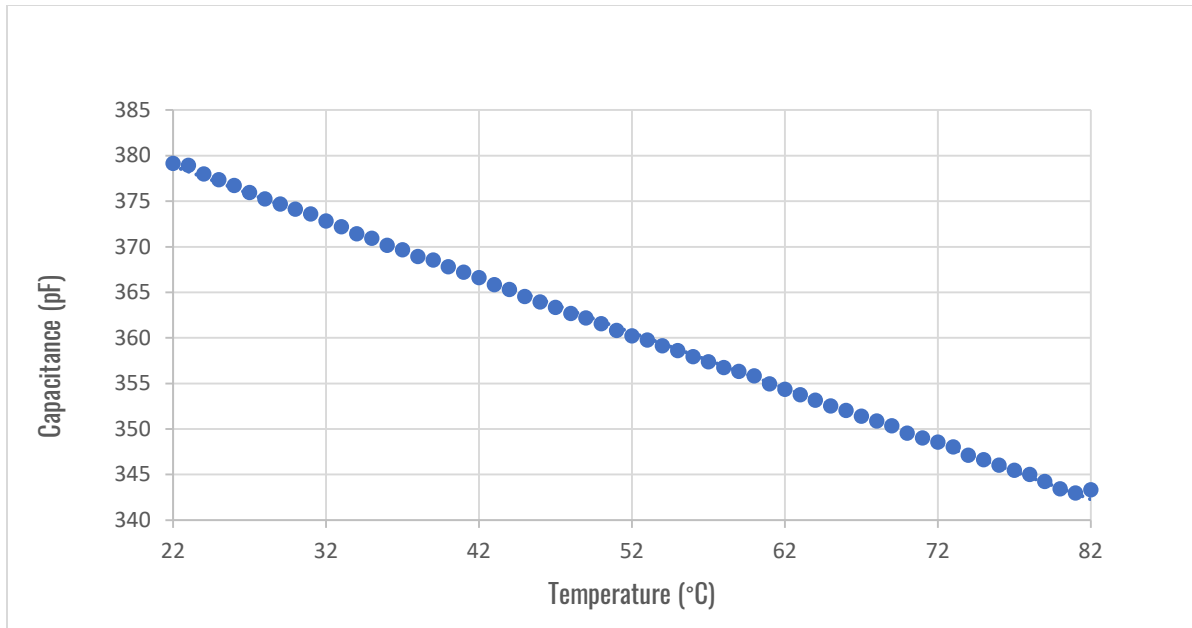


Figure 6: Average temperature response of a StretchFABRIC sensor over five cycles of heating and cooling

Temperature range	22 °C – 82 °C
Capacitance range	379 pF – 343 pF
Sensitivity	- 0.60 pF / °C
Sensitivity as a percentage of base capacitance (22 °C)	- 0.16 % / °C

Application Note

- For applications with large temperature variance, a reference sensor can be used to compensate for the change in temperature.

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